

On general approach to optimal parameterization of polynomial curves

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- ▶ Standard problem in CAGD:
 - Points $\mathbf{T}_j \in \mathbb{R}^d$ ($d \geq 2$), $j=0,1,\dots,n+1$, are given.
 - Find $a := t_0 < t_1 < \dots < t_n < t_{n+1} := b$ and parametric polynomial $\mathbf{p} := \mathbf{p}_{n+1}$ of degree $\leq n+1$

$$\mathbf{p}(t_j) = \mathbf{T}_j, \quad j = 0, 1, \dots, n+1.$$

- If n is large, replace \mathbf{p} by spline \mathbf{s} .

Main problem

- ▶ If $\{t_j\}_{j=0}^{n+1}$ is known, construction of \mathbf{p} is linear problem.
- ▶ Different choices of $\{t_j\}_{j=0}^{n+1}$ give different curves.
- ▶ How to choose the most appropriate sequence $\{t_j\}_{j=0}^{n+1}$?
- ▶ What are reasonable criteria?

Classical parameterizations

Assume $t_0 := 0$ and $t_{n+1} := 1$ (linear reparameterization).
 Possible choices for $\{t_j\}_{j=1}^n$ are:

- ▶ Uniform:

$$t_j := \frac{j}{n+1}, \quad j = 0, 1, \dots, n+1.$$

- ▶ Chord-length:

$$t_{j+1} = t_j + \frac{1}{L} \|\Delta \mathbf{T}_j\| = \frac{1}{L} \sum_{k=0}^j \|\Delta \mathbf{T}_k\|, \quad L = \sum_{k=0}^n \|\Delta \mathbf{T}_k\|.$$

- ▶ Centripetal:

$$t_{j+1} = \frac{1}{L} \sum_{k=0}^j \|\Delta \mathbf{T}_k\|^{1/2}, \quad L = \sum_{k=0}^n \|\Delta \mathbf{T}_k\|^{1/2}.$$

- ▶ Lee's generalization:

$$t_{j+1} = \frac{1}{L} \sum_{k=0}^j \|\Delta \mathbf{T}_k\|^\mu, \quad L = \sum_{k=0}^n \|\Delta \mathbf{T}_k\|^\mu, \quad \mu \in [0, 1].$$

Classical parameterizations

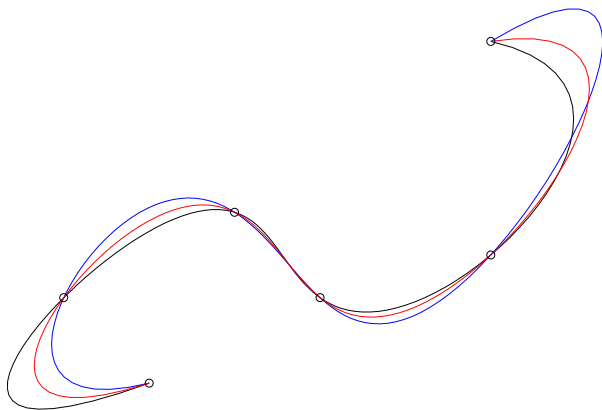


Figure: Various parameterizations: uniform (black), chord-length (blue) and centripetal (red).



Motivation

Let $[t_i]T = T_i$ and, for $k + \ell \geq 1$,

$$\begin{aligned} & [t_k, t_{k+1}, \dots, t_{k+\ell}]T \\ &= \frac{1}{t_{k+\ell} - t_k} ([t_{k+1}, \dots, t_{k+\ell}]T - [t_k, \dots, t_{k+\ell-1}]T). \end{aligned}$$

Interpolating polynomial \mathbf{p} in Newton form is

$$\mathbf{p}(t) = \sum_{k=0}^{n+1} (t - t_0)(t - t_1) \cdots (t - t_{k-1}) [t_0, t_1, \dots, t_k]T. \quad (1)$$

Motivation

A natural approach: minimize divided differences to get coefficients at higher order terms small.

- ▶ Define a nonlinear functional

$$\psi_\ell(\mathbf{t}; \mu) := \sum_{k=0}^{n+1-\ell} \|[t_k, t_{k+1}, \dots, t_{k+\ell}] \mathbf{T}\|^\mu, \quad (2)$$

where $1 \leq \ell \leq n+1$, $\mu > 0$, and

$$\mathcal{D} := \{\mathbf{t} \in \mathbb{R}^n \mid 0 < t_1 < t_2 < \dots < t_n < 1\}.$$

Motivation

- ▶ Functional $\psi_\ell(\cdot; \mu)$ is **positive** on \mathcal{D} and (at least for $\ell \leq 2$ **unbounded at the boundary** $\partial\mathcal{D}$). Namely:

Lemma

Let a sequence $\{\mathbf{T}_j\}_{j=0}^{n+1}$ of distinct points be given and $\ell = 1$ or $\ell = 2$. If $t_i \rightarrow t_j$ for some $i \neq j$, $0 \leq i, j \leq n+1$, then exists at least one $0 \leq k \leq n+1-\ell$

$$\| [t_k, t_{k+1}, \dots, t_{k+\ell}] \mathbf{T} \| \rightarrow \infty.$$

As a consequence, $\psi_\ell(\cdot; \mu)$ has **at least one global minimum** in \mathcal{D} for $\ell \leq 2$.

Particular examples

In particular, for $\ell = 1$ the global minimum is **unique**.

Lemma

Nonlinear functional $\psi_1(\cdot; \mu)$ has a **unique global minimum** on \mathcal{D} . It is given by

$$t_0 := 0, \quad t_{j+1} := \frac{1}{L} \sum_{k=0}^j \|\Delta \mathbf{T}_k\|^{\frac{\mu}{\mu+1}}, \quad j = 0, 1, \dots, n. \quad (3)$$

where

$$L = \sum_{k=0}^n \|\Delta \mathbf{T}_k\|^{\frac{\mu}{\mu+1}}.$$

Particular examples

For $\ell > 1$ the problem of minimization is **nonlinear**.
 Consider only the case $n = 1$.

- ▶ Points $\mathbf{T}_j \in \mathbb{R}^2$, $j = 0, 1, 2$ are given.
- ▶ Find quadratic polynomial parameterization $\boldsymbol{\rho} : [0, 1] \rightarrow \mathbb{R}^2$ such that

$$\boldsymbol{\rho}(t_j) = \mathbf{T}_j, \quad j = 0, 1, 2, \quad t_0 := 0 < t_1 < t_2 := 1.$$

- ▶ Let $t_1 := t$ and $\psi_2(t; \mu) = \|[0, t, 1] \mathbf{T}\|^\mu$. Find

$$\min_{0 < t < 1} \psi_2(t; \mu).$$

This leads to

$$\begin{aligned}
 g(t) = & (1-t)^3 d_0^2 - (1-t)^2 t d_0 d_1 \cos \varphi \\
 & + (1-t) t^2 d_0 d_1 \cos \varphi - t^3 d_1^2 = 0.
 \end{aligned}$$

where $d_j = \|\Delta T_j\|$, $j = 0, 1$, and φ an angle between ΔT_0 and ΔT_1 .

Lemma

Function g has precisely one root on $(0, 1)$.



Particular examples

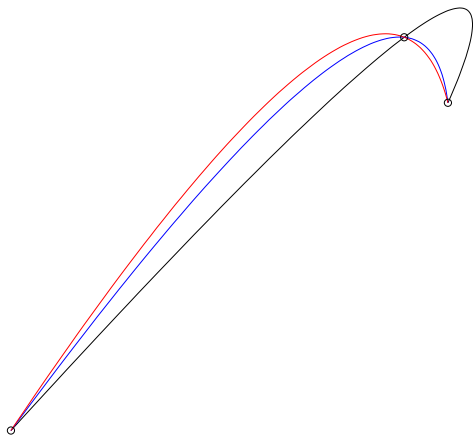


Figure: Various parameterizations on three points: uniform (black), centripetal (blue), minimal (red).

Optimizing higher order divided differences

- ▶ For arbitrary $\ell \geq 2$ and $n > 1$ only numerical algorithms are useful.
- ▶ **Uniqueness of the minimum is no more guaranteed.**
- ▶ Numerical evidences: minimum is not difficult to find, best behaviour for $\ell = 2$.
- ▶ For $\ell = 2$ second order divided differences are minimized \longrightarrow **curvature?**
- ▶ A **different functional** should be minimized?

Optimizing higher order divided differences

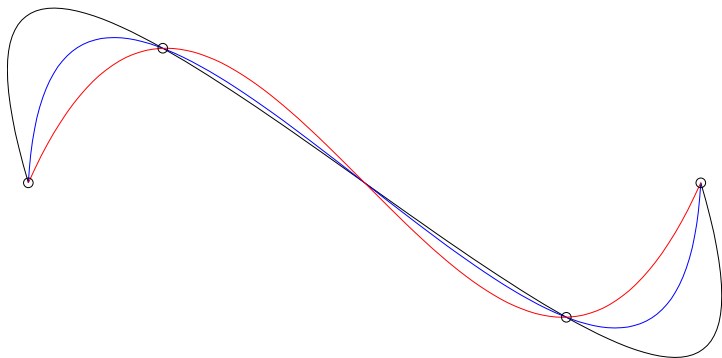


Figure: Various parameterization on four points: uniform (black), centripetal (blue), minimal with $\ell = 2$ and $\mu = 2$ (red).

Optimizing higher order divided differences

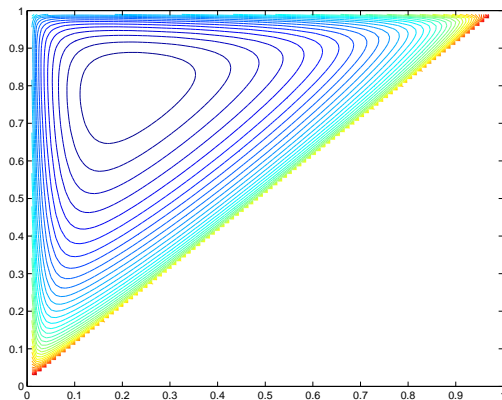


Figure: Contour plot of the functional $\psi_2(\cdot; 2)$ from the previous example in logarithmic scale.

Optimizing higher order divided differences

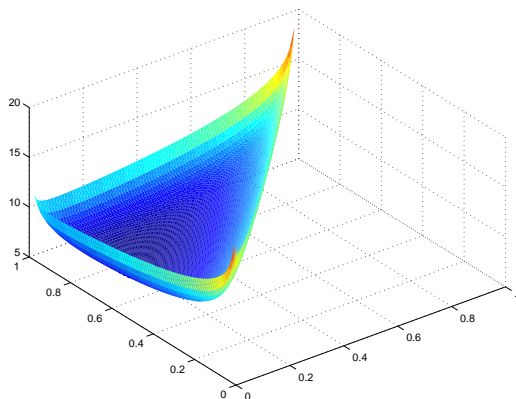


Figure: Surface plot of the functional $\psi_2(\cdot; 2)$ from the previous example in logarithmic scale.



Optimizing higher order divided differences

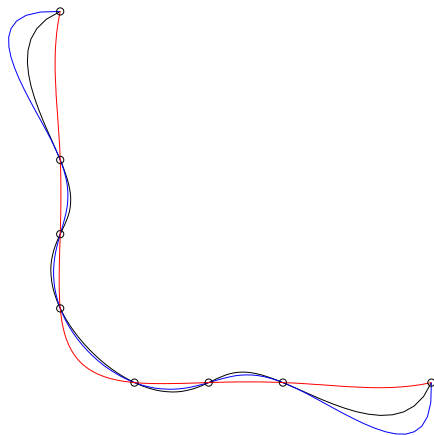


Figure: Various parameterizations on eight points: uniform (black), centripetal (blue), minimal with $\ell = 2$ and $\mu = 2$ (red).

- ▶ Suppose that a **global minimum** of the nonlinear functional $\psi_\ell(\cdot; \mu)$ defined by ▶(2) is **zero**.
- ▶ Obviously

$$[t_k, t_{k+1}, \dots, t_{k+\ell}] \mathbf{T} = \mathbf{0}, \quad k = 0, 1, \dots, n + 1 - \ell,$$

- ▶ Thus

$$[t_0, t_1, \dots, t_{k+\ell}] \mathbf{T} = \mathbf{0}, \quad k = 0, 1, \dots, n + 1 - \ell.$$

Höllig-Koch conjecture

- ▶ By (1)

$$\text{degree}(\mathbf{p}) \leq \ell - 1.$$

- ▶ The number of equations should be greater than the number of unknown parameters, thus

$$\ell \geq \left\lceil \frac{(d-1)n + 2d}{d} \right\rceil.$$

- ▶ Equality gives precisely Höllig-Koch conjecture.